

Introduction:

In our research we implement a machine learning algorithm using pre-trained convolutional neural networks to classify wildlife animals. The term "trained" refers to the models algorithm weights that are adjusted to better classify a given set of training images. We compare classification accuracy using models trained on individual trail cam images versus images of all cameras. The hypothesis here is that individual cameras will perform better even though their datasets are smaller due to similarity in the data.

Dataset:

The dataset we used for the experiments is composed of 24973 images taken by trail cameras on SSU Preserves. The trail cameras take a series of three images every time they detect motion. The dataset contains twenty three classes of images across six camera groups. Classes with a minimum of 200 images were used in these experiments reducing the number of classes to nine. This is done to prevent a negative influence on the systems classification accuracy by excluding classes that have a low amount of images that can be trained on. All the images below are examples of the database and underneath the class name is the confidence the trained CNN had in its prediction



railCamera EK004212.IF File: squirrel/NorthernTowerMeadowC True: human Pred: human (1.000)



True: squirrel

Pred: squirrel (0.962)



True: skunk Pred: skunk (0.962)

Deep Learning:

In this work, we explore using convolutional neural network (CNN) which are successive "layers" of neurons that learn to respond to image features such as color, texture, edges. These are combined in later layers to detect larger concepts such as faces, animals, etc. In particular we implement "transfer learning" a method where features pre-trained by the CNN are pulled for the new classification system to recognize images in your own database. In order to achieve this we used CNN model architecture called InceptionV3(Google Inc) which has been pre-trained on "imageNet" a database containing 1000 different categories. In order to complete the retraining process, we used an example script provided by TensorFlow, an open source machine learning software library developed by Google, and adapted it for our own case.



Experiment Setup: Base Experiment: In this experiment we are setting up results in which to compare our other two tests. This is run using all six camera groups with class that contain more than 200 images.

Experiment 1: In this experiment we split the images among their individual camera groups but continue to use the same nine classes.

Experiment 2: In this experiment we apply a 200 image minimum to each animal class for the individual cameras.

Using Pre-trained Convolutional Neural Networks to Classify Wildlife Animals

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ostROWCamera EK002600.IPG Pred: deer (0.999)

Evaluating on Individual Cameras:

In order to try to improve model accuracy, we try to obtain classifications on individual cameras. The reasoning behind this is that even though the size of individual datasets would decrease, the influence by the various backgrounds would decrease as well. What we consider as background is anything else in the image that is not the animal we are trying to classify. In some cases animals of a single class may more likely be seen in certain areas thus keeping the larger portion of images on a specific camera hopefully allowing for better accuracy



Results:

Base Experiment The following results are the model's accuracy on the test subset across all cameras. 5-fold Validation

Average Accuracy = correctly classified in a class/ total images of class Average Accuracy overall: 0.8579 | Standard Deviation: 0.0063

Average F1 Score overall = (2 * precision * recall)/(precision + recall) Average F1 Score overall: 0.8026 | Standard Deviation: 0.0887

Confusion Matrix for the 5th-fold Validation

					Predic	ted Label				
		bobcat	deer	human	nothing	possum	rabbit	skunk	squirrel	turkey
	bobcat	59	21	0	4	1	15	1	1	0
	deer	10	798	8	31	4	17	4	10	2
be	human	1	1	402	14	0	0	0	6	0
La	nothing	4	35	28	1741	27	50	33	120	26
Jal	possum	4	2	1	0	78	7	5	0	0
\cti	rabbit	8	21	0	25	6	287	4	14	5
4	skunk	0	4	0	1	3	3	105	0	0
	squirrel	1	18	2	40	1	14	0	408	6
	turkey	1	1	2	10	0	1	0	9	110

Experiment 1:

Results of Individual Cameras:

LowerTrailCamera Average Accuracy: 0.8884 | Standard Deviation: 0.0096 Average F1 Score overall: 0.8187 | Standard Deviation: 0.078 human nothing possum rabbit skunk squirrel turkey

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cat	51	3	0	2	0	3	0	с с	0	bobcat	235
r	0	59	3	9	0	13	1	. 1	. 0	deer	383
an	2	6	333	13	0	0	1	. 8	0	human	1772
ning	1	3	4	862	6	22	1	. 24	- 1	nothing	4740
sum	0	0	0	0	23	2	0	0	0	possum	135
oit	5	0	0	1	0	77	1	. 4	- 1	rabbit	454
nk	0	0	0	1	2	4	37	C	0	skunk	229
rrel	1	1	0	16	0	7	0	109	2	squirrel	692
еу	0	2	0	2	0	0	0	1	36	turkey	195
•											

NorthernTowerMeadowCamera Average Accuracy: 0.9064 | Standard Deviation: 0.0050 Average F1 Score overall: 0.7980 | Standard Deviation: 0.1402

	bobcat	deer	human	nothing	possum	rabbit	skunk	S	squirrel	turkey				
obcat	4	5	0	2	C)	0	0	0		0	bobcat	26	bo
eer	0	123	0	11	C)	0	0	0		0	deer	747	de
uman	0	0	2	0	C)	0	0	1		0	human	10	hı
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abbit	0	3	0	0	C)	3	0	0		0	rabbit	18	ra
kunk	0	1	0	0	C)	0	7	0		0	skunk	45	sk
auirrel	0	1	0	6	C)	0	0	69		2	squirrel	436	sc
urkev	0	0	0	0	C)	0	0	0	2	24	turkey	119	tu
/	-	-	-	-	-				-					

UpperTrailCamera Average Accuracy: 0.6053 | Standard Deviation: 0.0401 Average F1 Score overall: 0.6081 | Standard Deviation: 0.1950





Number	of	Images

Per class 575 bobcat

deer	4272
human	2200
nothing	10416
possum	515
rabbit	1806
skunk	590
squirrel	2397
turkey	643

UpperMostROWCamero

Average Accuracy: 0.7827 | Standard Deviation: 0.0237 Average F1 Score overall: 0.7001 | Standard Deviation: 0.1719



UperROWWoodChipFieldCamera

Average Accuracy: 0.8726 | Standard Deviation: 0.0075 Average F1 Score overall: 0.7204 | Standard Deviation: 0.1288

popcat	aeer		numan		notning	possum	rai	זוממ 🗄	skunk	squirrei	turkey			
	3	1		0	0	0		1	1	()	0	bobcat	
4	4	37		0	4	0		2	0	3	3	0	deer	2
	0	0		3	2	0		0	0	()	0	human	
	2	1		0	304	0		4	0	-	7	7	nothing	15
	0	0		0	0	0		2	0	-	L	0	possum	
	2	5		0	1	2		72	0	3	3	0	rabbit	4
	1	1		0	0	1		0	3	()	0	skunk	
	0	0		0	1	0		0	0	22	2	0	squirrel	1
	0	0		0	3	0		0	0	()	12	turkey	1

SODPlotCamera

Average Accuracy: 0.8562 | Standard Deviation: 0.0088 Average F1 Score overall: 0.7578 | Standard Devigtion: 0.2411

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bobcat	deer	human	nothing	possum	rabbit	skunk	squirrel	turkey		
1	0	0	3	0	0	1	1	0	bobcat	
0	149	0	8	1	0	1	1	0	deer	
0	1	46	0	0	0	0	0	0	human	
1	3	0	121	1	0	0	8	1	nothing	
0	0	0	0	33	1	0	2	0	possum	
0	0	0	2	0	2	0	2	0	rabbit	
1	0	0	1	1	C	25	1	0	skunk	
0	3	0	34	1	0	0	154	0	squirrel	
0	0	0	0	0	0	0	0	21	turkey	

Experiment 2:

Due to some cameras capturing lower numbers of certain kinds of animals implementing a minimum image asses on the overall accuracy.

LowerTrailCamera

Average Accuracy: 0.8901 | Standard Devic Average F1 Score overall: 0.8224 | Standard Deviation: 0.0739



Results Analysis:

Splitting the database up amongst the individual cameras as preformed in experiment 1 showed that certain cameras were better at classifying specific animal groups then others. UpperMostROWCamera(UMRC) is better at classifying bobcats than NorthernTowerMeadowCamera(NTMC), but NTMC is better at classifying turkeys than UMRC. This can be contributed by the differences in image quantities for these cameras. NTMC is also better at classifying skunks than UMRC even though their image quantities for these classes are similar. Meaning that the camera backgrounds are influencing these cameras differently.

Experiment 2 demonstrates an increase in classification accuracy due to the loss of influence by classes containing small image amounts. Individual camera groups were able to classify harder to classify images that the base experiment was not able to do. The image of the rabbit to the left is barely noticeable due to the glare. The base experiment classified the image as skunk while experiment 2 correctly classified the image with high confidence. To the right is a squirrel nearly out of the image yet again experiment 2 was able to classify.



Conclusion and Future Research:

- accuracy.
- levels in other cameras.
- have a low number of images.

Acknowledgements:

The database used in these test were provided by Dr. Chris Halle. This project has been funded by the Norwick award and a special thanks goes out to the family.

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UpperMostROV	VCamera

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		deer	nothing	rabbit	squirrel			
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	nothing	1	202	15	5	nothing	1163	
	rabbit		5 41	112	6	rabbit	767	

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0	127	squirrel	692		
				UperROWWoodChipFieldCamer	ā
/i	ation: (0.0050		Average Accuracy: 0.9560 Sto	and
\mathbf{C}	1 Devic	ntion · O	0635	Average F1 Score overall: 0.9238	3

rabbit

viation: 0.0050	Average Accuracy: 0.9560 Standard Deviation: 0.0126
d Deviation: 0.0635	Average F1 Score overall: 0.9238 Standard Deviation: 0
	deer nothing rabbit

/erage F1 Score overall: 0.9238 Standard Deviation: 0.0454					
deer nothing rabbit					
eer 32 6 7 deer 218					
othing 5 297 12 nothing 1587					
abbit 0 0 86 rabbit 422					

viation: 0.0160 Ird Deviation: 0.0575 el			UpperTrailCamera No Classes Contain at Least 200 Images
			bobcat 83 deer 195
4	deer	833	human 43
1	1 human 2	238	nothing 167
30	nothing	650	nossum 69
3	possum	200	rabbit 120
182	squirrel	916	skunk 83

• Each of these cameras receive different inputs so processing them as a group hurts

• Camera backgrounds are not similar so data pulled from these will alter confidence

• Some cameras record more images of a specific animal class than others so treating the cameras separately can improve classification confidence for these animals. • Splitting amongst individual cameras does hurt its ability to classify animal groups that

• Future work would involve testing data augmentation for classes that comprise of small datasets as well as feature extraction from earlier layers in the CNN.